

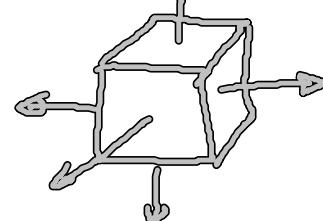
• Erinnerung:

$$\operatorname{div} \underline{\alpha}(r) = \nabla \cdot \underline{\alpha}(r)$$

Kartesische Koordinaten: $\operatorname{div} \underline{\alpha} = \frac{\partial}{\partial x} \alpha_x + \frac{\partial}{\partial y} \alpha_y + \frac{\partial}{\partial z} \alpha_z$

• Fluss = Normalkomponente von $\underline{\alpha}$ mal Fläche (Normale immer aus Volumen heraus!)

• $q(r) = \operatorname{div} \underline{\alpha} \Delta V$ misst Fluss aus ΔV heraus (6.43)



$q(r) = 0$... "was rein fließt, fließt raus"

> 0 ... "es fließt mehr raus als rein"
≈ Quelle

< 0 ... Senke

Bsp: $\underline{v}(r) = v_0 \underline{r} \rightarrow \operatorname{div} \underline{v} = 3v_0 \quad \left. \right\} (6.44)$
 \rightarrow überall Quellen!

• Regeln: (1) $\nabla \cdot (\underline{a} + \underline{b}) = \nabla \cdot \underline{a} + \nabla \cdot \underline{b}$
(2) $\nabla \cdot (f(r)\underline{a}) = f(r) \nabla \cdot \underline{a} + \underline{a} \cdot \nabla f(r) \quad \left. \right\} (6.45)$

Beweis: in kartesischen Koord.

• Zylinderkoordinaten:

$$\nabla \cdot \underline{\alpha}(r) = \left(e_S \frac{\partial}{\partial S} + e_Y \frac{1}{S} \frac{\partial}{\partial Y} + e_Z \frac{\partial}{\partial Z} \right) \cdot \left(\underline{\alpha} e_S + \alpha_Y e_Y + \alpha_Z e_Z \right)$$

Achtung: $\frac{\partial}{\partial \varphi} \underline{e}_r = \frac{\partial}{\partial \varphi} \begin{pmatrix} \cos \varphi \\ \sin \varphi \\ 0 \end{pmatrix} = \begin{pmatrix} -\sin \varphi \\ \cos \varphi \\ 0 \end{pmatrix} = \underline{e}_\varphi$

$$\frac{\partial}{\partial \varphi} \underline{e}_\varphi = -\underline{e}_r \quad \dots \text{nicht benötigt}$$

$$\frac{\partial}{\partial x_i} \underline{e}_j = 0 \quad , \quad x_i, i = 1, 2$$

(6.46) und $\underline{e}_i \cdot \underline{e}_j = \delta_{ij}$

$$\rightarrow \nabla \cdot \underline{g}(r) = \frac{2}{r^2} a_3 + \frac{1}{r} a_2 + \frac{1}{r} \frac{\partial}{\partial r} a_1 + \frac{2}{r^2} a_2$$

$$= \frac{1}{r} \frac{\partial(r a_2)}{\partial r} + \frac{1}{r} \frac{\partial}{\partial r} a_1 + \frac{2}{r^2} a_2$$

- Bsp: $\cdot \underline{E}(r) \sim -\frac{1}{r} \underline{e}_r \rightarrow \operatorname{div} \underline{E}(r) \sim \frac{1}{r^2} - \frac{1}{r^2} = 0, r \neq 0$
- $\cdot \underline{v}(r) = \omega r \underline{e}_\varphi \rightarrow \operatorname{div} \underline{v} = 0!$

- Kugel Koordinaten: $\underline{a} = a_r \underline{e}_r + a_\varphi \underline{e}_\varphi + a_\vartheta \underline{e}_\vartheta$ (6.47)

$$\begin{aligned} \nabla \cdot \underline{a}(r) &= \frac{\partial a_r}{\partial r} + \frac{2}{r} a_r + \frac{1}{r} \frac{\partial a_\varphi}{\partial \varphi} + \frac{1}{r \sin \vartheta} a_\vartheta + \frac{1}{r \sin \vartheta} \frac{\partial a_\vartheta}{\partial \varphi} \\ &= \frac{1}{r^2} \frac{\partial(r^2 a_r)}{\partial r} + \frac{1}{r \sin \vartheta} \frac{\partial(\sin \vartheta a_\vartheta)}{\partial \varphi} + \frac{1}{r \sin \vartheta} \frac{\partial a_\vartheta}{\partial \varphi} \end{aligned}$$

Basis: Übungen

Bsp: $\underline{g}(r) = \underline{r} = r \underline{e}_r \rightarrow \operatorname{div} \underline{g} = \frac{\partial r}{\partial r} + \frac{2}{r} r = 3!$ (vgl. 6.36)

6.6 Rotation

• Def: Rotation eines Vektorfeldes $\underline{a}(\underline{r})$

$$\text{rot } \underline{a}(\underline{r}) = \nabla \times \underline{a}(\underline{r}) \quad (6.49)$$

... Vektorfeld = Wirbelfeld von $\underline{a}(\underline{r})$

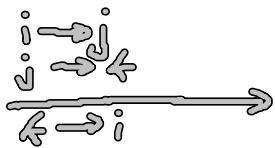
• Kartesische Koord:

$$\nabla = \xi_i \frac{\partial}{\partial x_i}, \quad \underline{a}(\underline{r}) = a_i \xi_i, \quad ; x_i = \sqrt{x^2}$$

$$\rightarrow \nabla \times \underline{a}(\underline{r}) = \left(\xi_i \frac{\partial}{\partial x_i} \right) \times (a_j(\underline{r}) \xi_j) \quad | \quad \varepsilon_{312}$$

$$\text{mit } \xi_i \times \xi_j = \varepsilon_{ijk} \xi_k \quad (2.23) \quad | \quad \begin{matrix} \varepsilon_{123} \\ \varepsilon_{213} \\ \varepsilon_{312} = 1 \end{matrix}$$

$$[\frac{\partial}{\partial x_i} \xi_j = 0] = \frac{\partial}{\partial x_i} a_j(\underline{r}) \underbrace{\varepsilon_{ijk} \xi_k}_{\varepsilon_{kij}}$$



$$\nabla \times \underline{a}(\underline{r}) = \varepsilon_{ijk} \left(\frac{\partial}{\partial x_j} a_k \right) \xi_i \quad (6.50)$$

$$[\nabla \times \underline{a}]_x = \frac{\partial}{\partial y} a_z - \frac{\partial}{\partial z} a_y$$

$$[\nabla \times \underline{a}]_y = \frac{\partial}{\partial z} a_x - \frac{\partial}{\partial x} a_z \quad \} \quad (6.51)$$

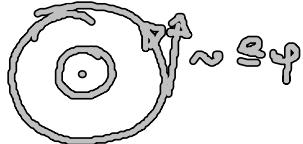
$$[\nabla \times \underline{a}]_z = \frac{\partial}{\partial x} a_y - \frac{\partial}{\partial y} a_x$$

Deutung:

$$\text{rot } \underline{a}(\underline{r}) = \nabla \times \underline{a}(\underline{r}) \text{ identifiziert local } (6.52)$$

Wirbel von Vektorfeldern

Bsp 1: $\underline{v} = \underline{\omega} \times \underline{r}$ (6.53) ... Prototyp eines Wirbels im Geschw. feld



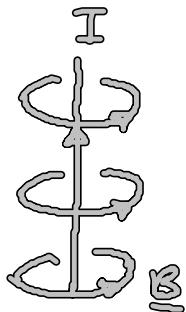
$$\underline{\omega} = \frac{1}{2} \underline{r} \times \underline{v} \dots \text{Wirbelsstärke}$$

$$\text{Beweis: } \underline{\text{rot}} \underline{v} = \underline{\nabla} \times (\underline{\omega} \times \underline{r})^{00}$$

$$\text{Hilfsformel: } \underline{a} \times (\underline{b} \times \underline{c}) = \underline{b} (\underline{a} \cdot \underline{c}) - \underline{c} (\underline{a} \cdot \underline{b})$$

$$\begin{aligned} &= \underbrace{[\underline{\omega} (\underline{\nabla} \cdot \underline{r})]}_3 - \underbrace{(\underline{\omega} \cdot \underline{\nabla}) \underline{r}}_{\underline{\omega}; \frac{\partial}{\partial x_j} \underline{r} = \underline{\omega}} \\ &= 3\underline{\omega} - \underline{\omega} \quad = 2\underline{\omega} \quad \text{qed} \end{aligned}$$

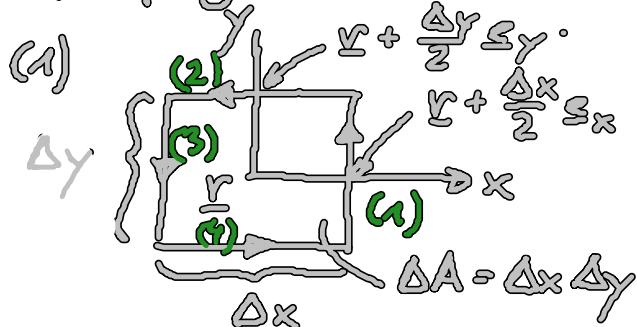
Bsp 2: Strom Leiter:



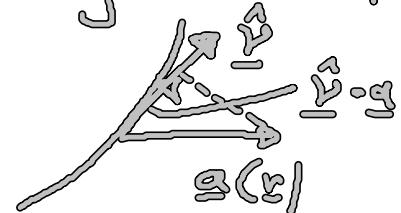
$$\underline{\text{rot}} \underline{B} \sim \underline{I} \quad (6.55)$$

(Maxwell-Gl.)

Bsp 3: Maß für Wirbel um Flächen element $\Delta A = \Delta x \Delta y$



(2) Tangential komp.



Summiere Tangential komp. von $\underline{s}(v)$ an ge schlossenem Weg \rightarrow Verwirbelung (6.56)

„Achtung: Weg wird im mathematischen pos. Sinn orientiert!“

$$\rightarrow \underbrace{[\alpha_y(r + \frac{\Delta x}{2} \varepsilon_x) - \alpha_y(r - \frac{\Delta x}{2} \varepsilon_x)]}_{\underline{g \cdot \varepsilon_y} \quad (1)} \Delta y$$

$$+ \underbrace{[\alpha_x(r - \frac{\Delta y}{2} \varepsilon_y) - \alpha_x(r + \frac{\Delta y}{2} \varepsilon_y)]}_{\underline{g \cdot \varepsilon_x} \quad (4)} \Delta x$$

$$\begin{aligned} & \text{Taylor} \left[\alpha_y(r) + \frac{\Delta x}{2} \frac{\partial}{\partial x} \alpha_y - \alpha_y(r) + \frac{\Delta x}{2} \frac{\partial}{\partial x} \alpha_y \right] \Delta y \\ & + \left[\alpha_x(r) - \frac{\Delta y}{2} \frac{\partial}{\partial y} \alpha_x - \alpha_x(r) - \frac{\Delta y}{2} \frac{\partial}{\partial y} \alpha_x \right] \Delta x \\ & = \left(\frac{\partial}{\partial x} \alpha_y - \frac{\partial}{\partial y} \alpha_x \right) \Delta x \Delta y = [\text{rot } \underline{a}]_z \Delta x \Delta y \end{aligned}$$

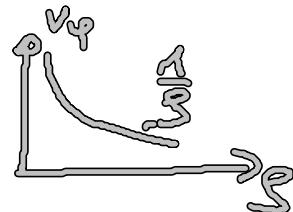
bed. Orientierung


$\text{rot } \underline{a} \Delta A = \underline{D} \times \underline{a} \Delta A$
 misst ω wirbel um ΔA

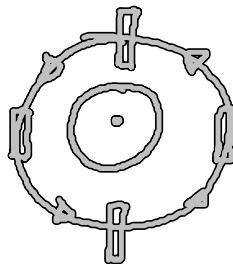
(6.57)

$$\text{Bsp 4: } \underline{\omega}(r) = \frac{90^\circ}{r} \varepsilon_z \times \underline{e}_y = \frac{90^\circ}{r} \varepsilon_y \quad (6.58)$$

$$\text{o. B.: } \text{rot } \underline{\omega} = 0, \quad r \neq 0$$



Deutung:



• Zylinder-/Kugelwind: $\text{rot } \underline{a}$ berechenbar

• Regeln: (1) $\underline{D} \times (\underline{a} + \underline{b}) = \underline{D} \times \underline{a} + \underline{D} \times \underline{b}$ (6.59)

(2) $\underline{D} \times (f(r)\underline{a}) = f(r) \underline{D} \times \underline{a} + [f'(r)] \times \underline{a}$

Beweis: in kugelsymmetrische Kond.

