

14.5 Kanonische Transformationen

• Motivierende Idee: [lat. bestangepaßt]

alle q_j zyklisch & $\frac{\partial H}{\partial t} = 0$

$$\rightarrow \dot{p}_j = -\frac{\partial H}{\partial q_j} = 0 \rightarrow p_j = \alpha_j = \text{konst.}$$

$$\rightarrow H = H(\alpha_1, \dots, \alpha_s) \rightarrow \dot{q}_j = \frac{\partial H}{\partial \alpha_j} = \omega_j(\alpha_1, \dots, \alpha_s) = \text{konst.}$$

$$\rightarrow \boxed{q_j = \omega_j t + \beta_j} \quad (14.41)$$

Bem: (i) (14.41) definiert integrale Systeme (... „die Ausnahme“ ...)

(ii) die Regel: nicht-integrale Systeme Bsp: 3-Körper-Problem

Ziel: Trafo: $\{q_j, p_j\} \rightarrow \{Q_k, P_k\}$, so daß alle Q_k zyklisch!

• Bisher: Punkttransformationen: $Q_k = Q_k(\{q_j\}, t)$

Beh: Punkttrafos lassen die Lagrange Gln. forminvariant

Bew: Umkehrung: $q_j = q_j(\{Q_k\}, t) \rightarrow \dot{q}_j = \sum_k \frac{\partial q_j}{\partial Q_k} \dot{Q}_k + \frac{\partial q_j}{\partial t} \quad (*)$

Zeige: $\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_j} - \frac{\partial L}{\partial q_j} = 0!$

$$= \sum_j \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \frac{\partial \dot{q}_j}{\partial \dot{Q}_k} \right) - \sum_j \left(\frac{\partial L}{\partial q_j} \frac{\partial q_j}{\partial Q_k} + \cancel{\frac{\partial L}{\partial q_j} \frac{\partial \dot{q}_j}{\partial Q_k}} \right)$$

(*) $\frac{\partial q_j}{\partial Q_k}$

$$\left(\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_j} \right) \frac{\partial q_j}{\partial Q_k} + \cancel{\frac{\partial L}{\partial q_j} \frac{d}{dt} \frac{\partial q_j}{\partial Q_k}}$$

$$= \sum_j \underbrace{\left(\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_j} - \frac{\partial L}{\partial q_j} \right)}_{=0} \frac{\partial q_j}{\partial Q_k} = 0 \checkmark$$

• jetzt

kanonische Trafos: $Q_k = Q_k(\{q_j\}, \{p_j\}, t)$ (14.43)

$P_k = P_k(\{q_j\}, \{p_j\}, t)$

wenn Hamiltonsche Bew.gln. forminvariant bleiben
bzgl. neuer Hamiltonfunktion $\bar{H} = \bar{H}(\{Q_k\}, \{P_k\}, t)$

äquivalent: $L(\{q_j\}, \{\dot{q}_j\}, t) \stackrel{\text{kanon. Trafo}}{=} L(\{Q_k\}, \{\dot{Q}_k\}, t) + \frac{d}{dt} F$

Legendre
↔
Trafo

$\sum_j p_j \dot{q}_j - H = \sum_j P_j \dot{Q}_j - \bar{H} + \frac{d}{dt} F$ (14.45) vgl. Kap. 13.5c)

erzeugende Funktion F:

(i) bestimmt kanonische Trafo!

(ii) soll also von $\{q_j\}, \{p_j\}, \{Q_j\}, \{P_j\}$ abhängen

2 F unabhängig
2 F abhängige Variable [vgl. (14.43)]

→ 4 Möglichkeiten

$F_1(\{q_j\}, \{Q_j\}, t)$	$F_2(\{q_j\}, \{p_j\}, t)$	(14.46)
$F_3(\{p_j\}, \{Q_j\}, t)$	$F_4(\{p_j\}, \{P_j\}, t)$	

(i) $F_1(\{q_j\}, \{Q_j\}, t)$:

$$\text{Bilde: } \frac{d}{dt} F_1 = \sum_j \left(\frac{\partial F_1}{\partial q_j} \dot{q}_j + \frac{\partial F_1}{\partial Q_j} \dot{Q}_j \right) + \frac{\partial F_1}{\partial t}$$

in (14.45) & Kraft. vgl. bei q_j, Q_j , da $\{q_j\}, \{Q_j\}$ unabh. Variable

$\frac{d}{dt} q_j \rightarrow$

$$p_j = \frac{\partial F_1}{\partial \dot{q}_j}$$

$\frac{d}{dt} Q_j \rightarrow$

$$p_j = - \frac{\partial F_1}{\partial \dot{Q}_j}$$

Rest \rightarrow

$$H = H + \frac{\partial F_1}{\partial t}$$

Umkehrung $\rightarrow Q_k = Q_k(\{q_j\}, \{p_j\}, t)$

$$\rightarrow p_k = p_k(\{q_j\}, \{Q_j\}, t)$$

$$= p_k(\{q_j\}, \{p_j\}, t)$$

... F_1 erzeugt kanon. Trafo

(ii) $F_2(\{q_j\}, \{p_j\}, t) \stackrel{\text{Leg. Trafo}}{=} F_1 + \sum_j p_j Q_j$ (14.48)

$$Q_j \rightarrow -p_j$$

$$p_j = - \frac{\partial F_1}{\partial \dot{Q}_j}$$

Kanone der
Legendre
Trafo

$$p_j = \frac{\partial F_2}{\partial \dot{q}_j}$$

$$Q_j = + \frac{\partial F_2}{\partial p_j}$$

$$H = H + \frac{\partial F_2}{\partial t}$$

... F_2 erzeugt kanon. Trafo.

(iii) $F_3(\{p_j\}, \{Q_j\}, t) \stackrel{\text{Leg. Trafo}}{=} F_1 - \sum_j p_j q_j$ (14.50)

→

$$\begin{aligned} q_j &= - \frac{\partial F_3}{\partial p_j} \\ p_j &= - \frac{\partial F_3}{\partial Q_j} \\ \bar{H} &= H + \frac{\partial F_3}{\partial t} \end{aligned} \quad (14.51)$$

... F_3 erzeugt kanon. Trafo

(iv) $F_4(\{p_j\}, \{Q_j\}, t) \stackrel{\text{leg. Trafo}}{=} F_1 + \sum_j p_j Q_j - \sum_j p_j q_j \quad (14.52)$

$$\begin{aligned} q_j &= - \frac{\partial F_4}{\partial p_j} \\ Q_j &= \frac{\partial F_4}{\partial p_j} \\ \bar{H} &= H + \frac{\partial F_4}{\partial t} \end{aligned} \quad (14.53)$$

... F_4 erzeugt kanon. Trafo

• Beispiele:

(i) identische Trafo: $F_2 = \sum_j q_j p_j \rightarrow \begin{aligned} p_j &= \frac{\partial F_2}{\partial q_j} = p_j \\ Q_j &= \frac{\partial F_2}{\partial p_j} = q_j \quad ! \\ \bar{H} &= H \end{aligned}$

(ii) Punktrafo = kanon. Trafo !

$$F_2 = \sum_j f_j(\{q_k\}, t) p_j \xrightarrow{Q_j = \frac{\partial F_2}{\partial p_j}} Q_j = f_j(\{q_k\}, t), \quad \bar{H} = H + \frac{\partial F_2}{\partial t}$$

(iii) $F_1 = \sum_j q_j Q_j \rightarrow \left. \begin{aligned} p_j &= \frac{\partial F_1}{\partial q_j} = Q_j \\ p_j &= - \frac{\partial F_1}{\partial Q_j} = -q_j \end{aligned} \right\} \text{Vertauschung von Impulsen}$

(iv) harmonischer Oszillator: $(x, p) = (q, p)$

$$H = \frac{p^2}{2m} + \frac{m\omega^2}{2} q^2 \quad (14.54) \quad \text{mit Federkonst. } f = m\omega^2$$

$$F_1 = \frac{m}{2} \omega q^2 \cot Q \longrightarrow p = \frac{\partial F_1}{\partial q} = m\omega q \cot Q \quad (1)$$

$$p = -\frac{\partial F_1}{\partial Q} = \frac{m\omega q^2}{2} \frac{1}{\sin^2 Q} \quad (2)$$

$$(2) \longrightarrow q = \sqrt{\frac{2P}{m\omega}} \sin Q \quad (3) \quad \left. \vphantom{\begin{matrix} (2) \\ (3) \end{matrix}} \right\} \text{kanon. Umkehrtrafo !!}$$

$$(3) \text{ in } (1) \longrightarrow p = \sqrt{2m\omega P} \cos Q \quad (4)$$

$$(3)(4) \text{ in } H: H = \bar{H} = \omega P \cos^2 Q + \omega P \sin^2 Q$$

$$\longrightarrow H = \omega P \longleftrightarrow \text{Impuls } P = \frac{\text{Energie } E = H}{\omega} \quad 0$$

$$Q \dots \text{zyklisch Koord.} \longrightarrow \text{Bewgl. } \dot{Q} = \frac{\partial H}{\partial p} = \omega$$

$$\longrightarrow Q = \omega t + \alpha$$

$$\longrightarrow q \stackrel{(3)}{=} \sqrt{\frac{2E}{m\omega^2}} \sin(\omega t + \alpha) \quad \checkmark$$

15. Hamilton-Jacobische Theorie

• nur Skizzierung!

• Grundidee:

Ges: kanonische Trafo auf

$$\begin{aligned} Q_k &= \beta_k = \text{konst.} \stackrel{\text{z.B.}}{=} q_k(0) \\ p_k &= \alpha_k = \text{konst.} = p_k(0) \end{aligned} \quad (15.1)$$

25 Integriert
konst. des Systems

damit Hamilton ~~bes~~ gl.

$$(14.4) \quad \left. \begin{aligned} 0 = \dot{Q}_k &= \frac{\partial \bar{H}}{\partial P_k} \\ 0 = \dot{P}_k &= -\frac{\partial \bar{H}}{\partial Q_k} \end{aligned} \right\} \text{o.B.d.A.} \quad \boxed{\bar{H} = H + \frac{\partial F}{\partial t} = 0} \quad (15.2)$$

mit $\bar{H} = H + \frac{\partial F}{\partial t}$

• erzeugende Fkt.? [vgl. Kap. 14.5]

$$\boxed{F_2(\{q_j\}, \{P_j\} = \{\alpha_j\}, t) = S(\{q_j\}, \{\alpha_j\}, t)} \quad (15.3)$$

... Hamilton-Jacobische - Wirkungsfkt.
(Hamiltonsche Prinzipalfkt.)

mit $\boxed{P_j = \frac{\partial S}{\partial q_j}} \quad (14.49)$

in (15.2) \rightarrow $\boxed{H(\{q_j\}, \{\frac{\partial S}{\partial q_j}\}, t) + \frac{\partial S}{\partial t} = 0} \quad (15.4)$

... Hamilton-Jacobische - Dgl. für S!

Bem: Hamiltonsche Theorie
Löse 2f gewöhn. Dgl.
1. Ordnung in Zeit

$$\dot{q}_j = \frac{\partial H}{\partial p_j}$$

$$\dot{p}_j = -\frac{\partial H}{\partial q_j}$$

äquivalent
 \longleftrightarrow
zu

Hamilton-Jacobische
Theorie
S als Lsg. von (15.4)
nichtlineare partielle
Dgl. 1. Ordnung
in f+1 Variable q_j, t