

English summary:

4.1 Legendre transform

$$g(a) = x \frac{df}{dx} - f(x), \text{ applied to } L \text{ and } \dot{q} : \dot{q} \frac{\partial L}{\partial \dot{q}} - L = \dot{q} p - L$$

Hamilton function ("Hamiltonian"):

$$H(q_1, \dots, q_f, p_1, \dots, p_f, t) = \sum_k \dot{q}_k p_k - L(q_1, \dots, q_f, \dot{q}_1, \dots, \dot{q}_f, t)$$

4.2 Canonical equations of Hamilton

$$\left. \begin{aligned} \dot{q}_k &= \frac{\partial H}{\partial p_k} \\ \dot{p}_k &= - \frac{\partial H}{\partial q_k} \end{aligned} \right\} \begin{aligned} &2f \text{ differential equations of } 1^{\text{st}} \text{ order} \\ &(\text{compare Lagrange's equations of } 2^{\text{nd}} \text{ kind}) \end{aligned}$$

for scleronomous constraints, conservative forces:

$$H = T + V : \text{total energy} \quad (\text{conserved for temporal translational invariance})$$

Fortsetzung von Kapitel 4.2

Anwendungschema des Hamilton-Formalismus:

(i) Wähle generalisierte Koordinaten $q = (q_1, \dots, q_f)$

(ii) Transformation $r_i = r_i(q_1, \dots, q_f, t)$, $\dot{r}_i = \dot{r}_i(q, \dot{q}, t)$ $i=1, \dots, N$

(iii) $L(q, \dot{q}, t) = T - V$ (konservative Kräfte)

(iv) generalisierte Impulse: $p_k = \frac{\partial L}{\partial \dot{q}_k} \Rightarrow p_k = p_k(q, \dot{q}, t)$

Umkehrung $\Rightarrow \dot{q}_k = \dot{q}_k(q, p, t)$

(v) Legendre-Transformation: $H(q, p, t) = \sum_{k=1}^f \dot{q}_k p_k - L(q, \dot{q}, t)$

(vi) Kanonische Gleichungen: $\dot{q}_k = \frac{\partial H}{\partial p_k}$, $\dot{p}_k = -\frac{\partial H}{\partial q_k}$ aufstellen & integrieren

Beispiele:

(a) 1 Teilchen in Zylinderkoordinaten ohne Zwangsbedingungen

(i) $q_1 = r$, $q_2 = \varphi$, $q_3 = z$

(ii) $x = r \cos \varphi$, $\dot{x} = \dot{r} \cos \varphi - r \sin \varphi \dot{\varphi}$
 $y = r \sin \varphi$, $\dot{y} = \dot{r} \sin \varphi + r \cos \varphi \dot{\varphi}$

(iii) $T = \frac{m}{2} (\dot{r}^2 + r^2 \dot{\varphi}^2 + \dot{z}^2)$, $V = V(r, \varphi, z)$

$\Rightarrow L(r, \varphi, z, \dot{r}, \dot{\varphi}, \dot{z}) = T - V$

(iv) generalisierte Impulse:

$p_r = \frac{\partial L}{\partial \dot{r}} = m \dot{r}$ Radialimpuls

$p_\varphi = \frac{\partial L}{\partial \dot{\varphi}} = m r^2 \dot{\varphi}$ z-Komponente des Drehimpulses (L_z)

$p_z = \frac{\partial L}{\partial \dot{z}} = m \dot{z}$ z-Komponente des Impulses

(v) $H = p_r \dot{r} + p_\varphi \dot{\varphi} + p_z \dot{z} - L = \frac{1}{m} \left(p_r^2 + \frac{p_\varphi^2}{r^2} + p_z^2 \right) - \frac{1}{2m} \left(p_r^2 + \frac{p_\varphi^2}{r^2} + p_z^2 \right) + V$

$= \frac{1}{2m} \left(p_r^2 + \frac{p_\varphi^2}{r^2} + p_z^2 \right) + V(r, \varphi, z)$

(vi) $\dot{r} = \frac{\partial H}{\partial p_r} = \frac{p_r}{m}$, $\dot{p}_r = -\frac{\partial H}{\partial r} = \frac{p_\varphi^2}{m r^3} - \frac{\partial V}{\partial r}$

$\dot{\varphi} = \frac{\partial H}{\partial p_\varphi} = \frac{p_\varphi}{m r^2}$, $\dot{p}_\varphi = -\frac{\partial H}{\partial \varphi} = -\frac{\partial V}{\partial \varphi}$

$\dot{z} = \frac{\partial H}{\partial p_z} = \frac{p_z}{m}$, $\dot{p}_z = -\frac{\partial H}{\partial z} = -\frac{\partial V}{\partial z}$



spezielles Potential: $V(r)$ ($\hat{=}$ Zentralpotential bei ebener Bewegung)

$\dot{p}_r = \frac{p_\varphi^2}{m r^3} - \frac{\partial V}{\partial r}$

$\left. \begin{matrix} \dot{p}_\varphi = 0 \\ \dot{p}_z = 0 \end{matrix} \right\} \begin{matrix} \varphi \text{ und } z \text{ sind zyklische Variable} \\ \Rightarrow p_\varphi = \text{const. (Drehimpulserhaltung)} \\ p_z = \text{const.} = 0 \text{ (ebene Bewegung)} \end{matrix}$

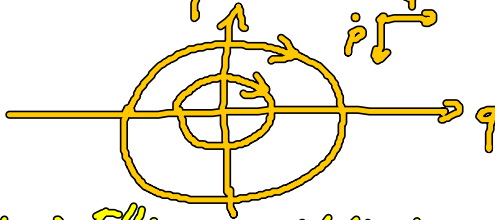
(b) 1-dimensionale harmonische Oszillatoren

$$L = \frac{m}{2} (\dot{q}^2 - \omega_0^2 q^2), \quad p = \frac{\partial L}{\partial \dot{q}} = m \dot{q}$$

$$H = \dot{q} p - L = \frac{p^2}{m} - \left[\frac{m}{2} \left(\frac{p^2}{m^2} - \omega_0^2 q^2 \right) \right] = \frac{p^2}{2m} + \frac{m}{2} \omega_0^2 q^2$$

$\frac{\partial L}{\partial t} = 0$, skleronomes System \Rightarrow Energieerhaltung $H = T + V = E$

$$\Rightarrow \frac{p^2}{2mE} + \frac{q^2}{\frac{2E}{m\omega_0^2}} = 1$$



Bahncurven im Phasenraum: Ellipsen mit Halbachsen

$$a = \sqrt{\frac{2E}{m\omega_0^2}}, \quad b = \sqrt{2mE}$$

$$\left. \begin{array}{l} \text{kanonische Gleichungen: } \dot{p} = -\frac{\partial H}{\partial q} = -m\omega_0^2 q \\ \dot{q} = \frac{\partial H}{\partial p} = \frac{p}{m} \end{array} \right\} \hat{=} \ddot{q} + \omega_0^2 q = 0$$

(definiert Richtungsfeld im Phasenraum)