



0. Introduction

We present a mean field approximation for the noisy Van der Pol system with time-delayed feedback below the Hopf bifurcation. It goes beyond the usual linearization of a stable focus and takes into account the nonlinearity self-consistently. We compare our analytical results to numerical simulations of the power spectral density and the correlation time in a regime with large noise intensity.

1. Model

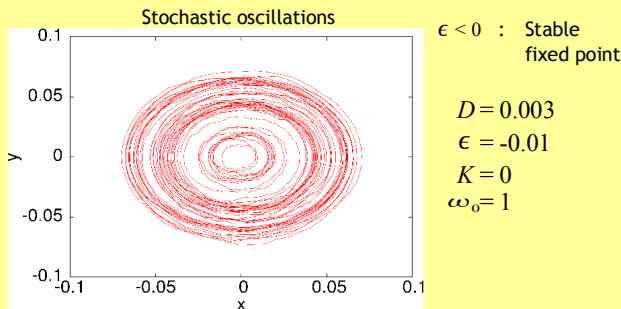
Noisy Van der Pol oscillator with time-delayed feedback control.

$$\begin{aligned} \dot{x} &= y \\ \dot{y} &= -\omega_0^2 x + (\epsilon - x^2)y + \underbrace{D\xi(t)}_{\text{noise}} + \underbrace{K[y(t-\tau) - y(t)]}_{\text{control}} \end{aligned} \quad (1)$$

- ϵ : Bifurcation parameter
- ξ : Gaussian white noise
- τ : Delay time
- ω_0 : Basic frequency
- D : Noise intensity
- K : Feedback strength

2. Noise induced oscillations

Phase portrait of the system below the Hopf bifurcation:



Aim: Use time-delayed feedback to control important oscillation features like coherence and timescales [1].

3. Multivariate Ornstein-Uhlenbeck process

$$d\mathbf{x}(t) = -\underline{A}\mathbf{x}(t)dt + \underline{B}d\mathbf{W}(t)$$

$\underline{A}, \underline{B} = \text{const.}, \mathbf{W}(t)$ Wiener process

Stationary variance matrix:

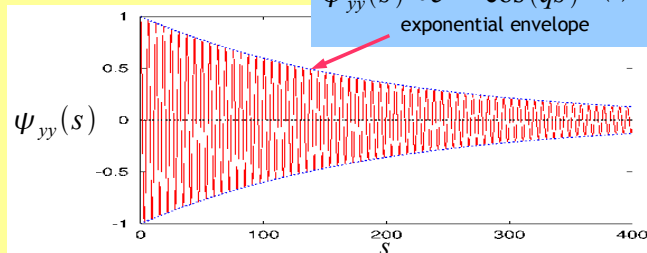
$$\underline{\sigma} = \langle \mathbf{x}(t), \mathbf{x}^T(t) \rangle = \frac{(\text{Det } \underline{A}) \underline{B} \underline{B}^T + [\underline{A} - (\text{Tr } \underline{A}) \underline{1}] \underline{B} \underline{B}^T [\underline{A} - (\text{Tr } \underline{A}) \underline{1}]^T}{2(\text{Tr } \underline{A})(\text{Det } \underline{A})} \quad (2)$$

Time correlation matrix:

$$\psi_{x_i x_j}(s) = \langle x_i(t-s), x_j^T(t) \rangle = \underline{\sigma} \underline{Q} \exp \left[\begin{pmatrix} (-p+iq)s & 0 \\ 0 & (-p-iq)s \end{pmatrix} \right] \underline{Q}^{-1} \quad (3)$$

eigenvalues of \underline{A} : $p \pm iq$ (4)

Autocorrelation function: $\psi_{yy}(s) \propto e^{-ps} \cos(qs)$ (5)
exponential envelope



4. Mean field approximation of the Van der Pol system

Self-consistent linearization of the Van der Pol system without control (for $\epsilon < 0$):

$$(\epsilon - x^2) \approx (\epsilon - \langle x^2 \rangle) = \tilde{\epsilon} \quad (6)$$

Van der Pol \longrightarrow Ornstein-Uhlenbeck

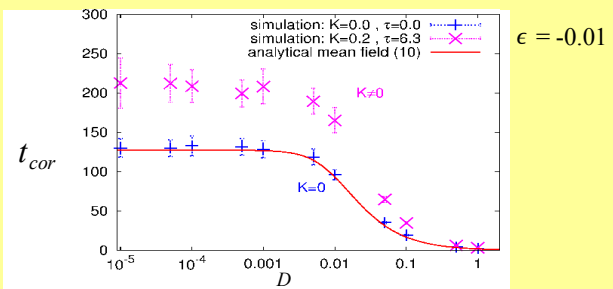
$$\underline{A} = \begin{pmatrix} 0 & -1 \\ \omega_0^2 & -\tilde{\epsilon} \end{pmatrix}, \underline{B} = \begin{pmatrix} 0 & 0 \\ 0 & D \end{pmatrix} \quad (7) \quad \text{with (2)} \quad \langle x^2 \rangle = \frac{D^2}{-2\tilde{\epsilon}\omega_0^2} \quad (8)$$

self-consistent mean field approximation with (6),(8):

$$\tilde{\epsilon} = \frac{\epsilon}{2} \left(1 + \sqrt{1 + \frac{2D^2}{\epsilon^2 \omega_0^2}} \right) \quad (9)$$

5. Mean field approximation of the correlation time

$$t_{cor} = \frac{1}{\psi_{yy}(0)} \int_0^\infty |\psi_{yy}(s)| ds \approx \frac{2}{\pi} \frac{1}{p} \stackrel{(4),(7)}{=} \frac{2}{\pi} \frac{2}{|\tilde{\epsilon}|} \quad (10)$$

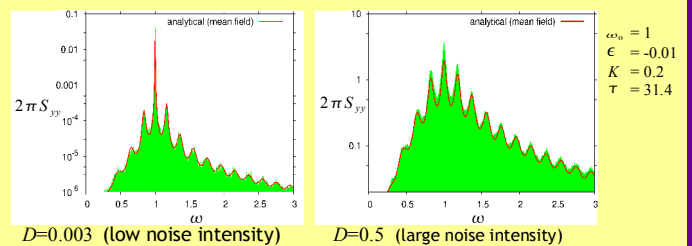


Very good agreement between theory and simulations over a large range of noise intensities

6. Analytical approximation of the power spectral density

Power spectral density S_{yy} of linearized Van der Pol oscillator [2] with mean field $\tilde{\epsilon}$

$$S_{yy}(\omega) = \frac{D^2}{2\pi} \frac{\omega^2}{[\omega^2 - \omega_0^2 + \omega K \sin(\omega\tau)]^2 + \omega^2 [\tilde{\epsilon} - K(1 - \cos(\omega\tau))]^2} \quad (11)$$



Very good agreement between theory and simulations even for large noise intensities

7. Conclusions

- Van der Pol system with time-delayed feedback can be approximated by a mean field model.
- Very good agreement of the power spectral density and correlation time with simulations even for large noise intensities.

8. References

[1] N. B. Janson, A. G. Balanov, and E. Schöll. Delayed feedback as a means of control of noise-induced motion. *Phys. Rev. Lett.* 93,010601 (2004)
 [2] E. Schöll, A. Balanov, N.B. Janson, and A. Neiman. Controlling stochastic oscillations close to a Hopf bifurcation by time-delayed feedback. *Stochastics and Dynamics* (2005)